



- What are the configurations of CoMoveIT Smart?

H3+F

Configuration 1

- Right Head – Steer Right
- Left Head – Steer Left
- Back Head – Drive Forward/Reverse
- Right or Left Foot – User Switch (Select Forward or Reverse), Access User Menu

Configuration 2

- Right Head – Steer Right
- Left Head – Steer Left
- Back Head – User Switch (Select Forward or Reverse), Access User Menu
- Right or Left Foot – Drive Forward/Reverse

H3+FF

Configuration 1

- Right Head – Steer Right
- Left Head – Steer Left
- Right Foot – Drive Forward/Reverse
- Left Foot – User Switch (Select Forward or Reverse), Access User Menu

Configuration 2

- Right Head – Steer Right
- Left Head – Steer Left
- Right Foot – User Switch (Select Forward or Reverse), Access User Menu
- Left Foot – Drive Forward/Reverse

Same configurations are still possible as H3+F

Rnet-Programming: CoMoveIT Smart Rnet settings for four-sensor configuration.



CoMoveIT

Profile Management	Profile 1	Profile 2	Profile 3
Profile Name	CoMoveIT Smart IN	CoMoveIT Smart M	CoMoveIT Smart OUT
Profile Enable	Yes	Yes	Yes
Mode Enable	[1234 78]	[1234 78]	[234 78]
Input Device Type	Omni	Omni	Omni
Input Device Subtype	All	All	All
Seat Reversal Profile	No	No	No
Allow Grab	Yes	Yes	Yes

Omni	CoMoveIT Smart IN	CoMoveIT Smart M	CoMoveIT Smart OUT
Global			
Profiled			
Port	1	1	1
Ports			
SID	Port 1	Port 2	
SID	3-Axis Switch	Proportional	
Switches	Port 1	Port 2	
User Switch	Normally Open	Normally Open	
Switch Detect	Off	Off	
9-Way Detect	Off	Off	
Switch Long	4.00 s	1.00 s	
Switch Medium	1.25 s	1.00 s	
Switch Debounce	50 ms	50 ms	
Double Click	0.0 s	0.3 s	
User Switch Detect	Off	Off	
9-Way SID Switch Detect	Off	Off	
Controls	Port 1	Port 2	

Remarks

- It is not possible to utilize all 5 sensors of CoMoveIT Smart simultaneously. The maximum number of sensors that can be used simultaneously is four.
- Above we mention the most obvious configurations with a typical use of the right and left head pads to be used to steer left and right. Nevertheless, it is perfectly possible to allow steering with the feet as well by simply connecting the foot pads to the indicated connection on the ECU (LH and RH). Or even using a mix of head or foot pad to steer left and right. This can happen if a client has an asymmetrical fixed neck position and can't make the turn to one or the other side for example.
- Some systems in the field might still exist with only 2 sensors (left and right) in the head pad ("H2").